

## Code Saturne on POWER8 clusters: First Investigations

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## **Technology**

- -Co-located finite volume, arbitrary unstructured meshes, predictor-corrector
- -350 000 lines of code, 37% Fortran, 50% C, 13% Python
- -MPI for distributed-memory and some OpenMP for shared-memory machines

## **Physical modeling**

- -Laminar and turbulent flows: k-epsilon, k-omega, SST, v2f, RSM, LES models
- -Radiative transfer
- -Coal, heavy-fuel and gas combustion
- -Electric arcs and Joule effect
- -Lagrangian module for particles tracking
- -Atmospheric modeling
- -ALE method for deformable meshes
- -Rotor / stator interaction for pump modeling, for marine turbines

## **Flexibility**

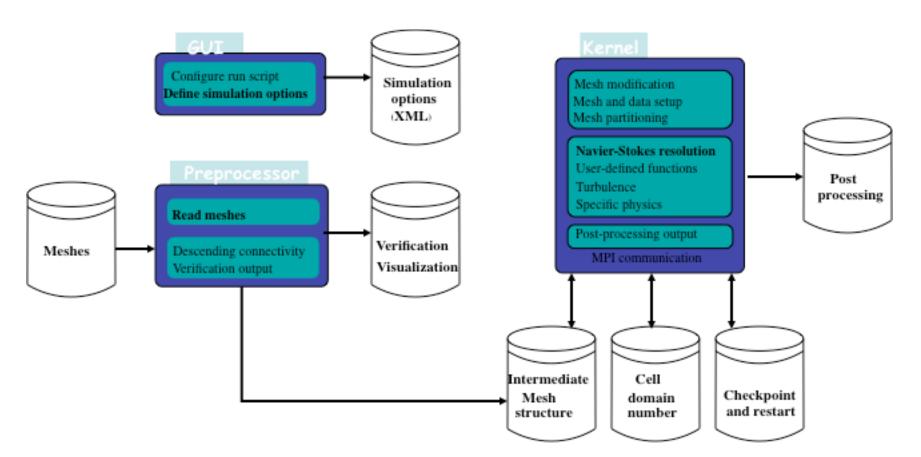
- -Portability (Unix, Linux, MacOS X and now Windows)
- -Graphical User Interface with possible integration within the SALOME platform





#### Reduced number of tools

- Each with rich functionality
- Natural separation between interactive and potentially long-running parts
- In-line (pdf) documentation

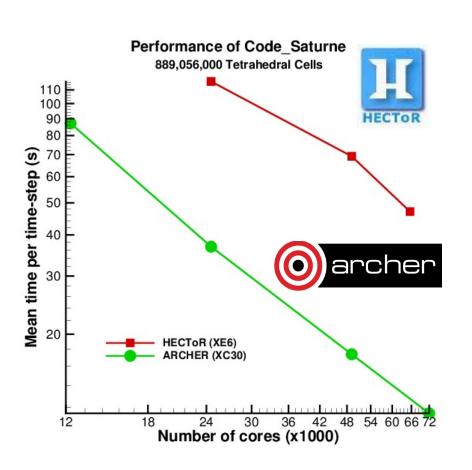




## Solver Scalability at Scale

#### **Comparison Cray XE6 – XC30**

#### Mesh generated by Mesh Multiplication Cube meshed using tetrahedral cells only



### 105B Cell Mesh (MIRA, BGQ)

Cores	Time in Solver
262,144	789.79 s
524,288	403.18 s

### 13B Cell Mesh (MIRA, BGQ)

MPI Tasks	Time in Solver
524,288	70.114 s
1,048,576	52.574 s
1,572,864	45.731 s

• **105B**: 16 ranks/node

• **13B**: 32 ranks/node





## Parallel 10 Performance

mesh: dumped to disk after MM: 19.853 TiB

checkpoint: 2 files

2.338 TiB and 3.053TiB

mesh: dumped to disk after MM: 2.483 TiB

checkpoint: 2 files

**0.306 TiB** and **0.391 TiB** 

### 105B Cell Mesh (MIRA, BGQ)

Cores	mesh	checkpoint
262,144	2697.15 s	659.72 s
524,288	2536.23 s	827.26 s

## 13B Cell Mesh (MIRA, BGQ)

MPI Tasks	mesh	checkpoint
524,288	458.51 s	409.60 s
1,048,576	595.52 s	541.26 s
1,572,864	732.28 s	591.66 s

• **105B**: 16 ranks/node

• **13B**: 32 ranks/node





## Description of the Machine

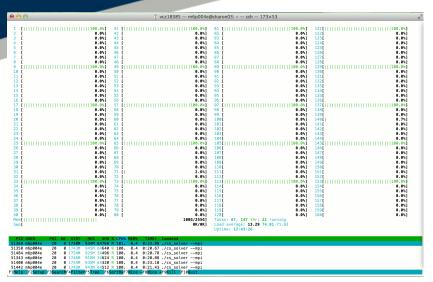
## Two types of IBM POWER8 nodes are tested

IBM Power System S822LC	IBM Power System S824L		
2 processors with 10 cores	2 processors with 12 cores		
Up to 8 logical cores	Up to 8 logical cores		
4 on-chip memory controllers (SCM)	8 on-chip memory controllers (DCM)		
256 GiB RAM/node	256 GiB RAM/node		
~2.92 GHz	~3.00GHz		
2 NVIDIA K80	2 NVIDIA K40		
2x GK210 per K80	1x GK180 per K40		
2,496 stream processors	2,880 stream processors		
12 GiB RAM	12 GiB RAM		

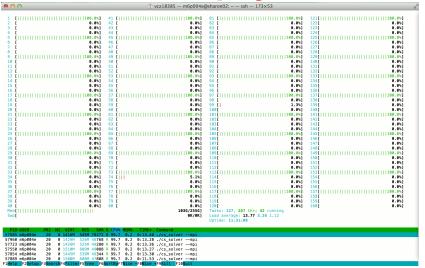
SMT expresses the number of virtual (hardware) cores or number of concurrent threads per physical core. This ratio can be set up without system reboot.



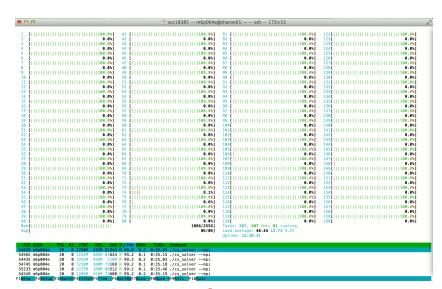
## **CPU Binding**



## SMT8 – 1 MPI/physical core



## SMT8 – 2 MPIs/physical core



## SMT8 – 4 MPIs/physical core



SMT8 – 8 MPIs/physical core



## Test Case Configuration

## 3-D lid-driven cavity test case

## Box 1x1x1 Mesh of 13 million tetrahedral cells Boundary conditions:

Top lid: horizontal velocity Spanwise direction: symmetry Last 3 boundaries: wall - Dirichlet

Re=100

## **Settings:**

Code\_Saturne V 4.2.1

METIS as a partitioner

Pressure Poisson equation:

All the cases use the native AMG of the code (as a preconditioner)

Except the last one which uses the PETSc library for comparison with with GPUs

(Conjugate Gradient)



## Comparison between 2 different half/full POWER8 nodes and 1 half/full x86 node

#### The x86 node is an Ivy Bridge E5-2697v2 2.7GHz

	S822LC			S824L			x86	
#C	T (s)	E (%)	#C	T(s)	E (%)	#C	T (s)	E (%)
10	26.50	-	12	21.51	-	12	31.61	-
20	16.43	81	24	11.80	91	24	25.33	62

#### All the runs are performed using SMT8 on the POWER8 nodes

For the "half node" simulations, the runs are using 2 sockets half loaded

N.B: The simulation using 1 S824L node is more than twice as fast as the one using the x86 node.





## The tests are carried out from 20 (24) MPI tasks on

IBM Power Sy	stem S822LC	IBM Power System S824L		
	PE/XL		PE/XL	
#C	T(s)	#C	T(s)	
20	16.43	24	11.80	
40	14.35	48	9.64	
80	14.38	96	9.62	
160	14.75	192	11.10	

The runs are performed are all using SMT8, with respectively 20 (24) MPIs, 40 (48) MPIs, 80 (96) MPIs and 160 (192) MPIs

Performance is lost when not fully utilising the system. If logical cores are unused, it is better to reconfigure (dynamically) the system to dedicate all hardware resources to the running threads.





## The tests are carried out using 20 MPI tasks

IBM Power System S822LC					
	OPENMPI/GNU				
#T	T (s) SP				
1	18.49	1.00			
2	16.01	1.16			
4	14.20	1.30			

## All the runs are using SMT8

Performance is lost when not fully utilising the system. If logical cores are unused, it is better to reconfigure (dynamically) the system to dedicate all hardware resources to the running threads.



## The PETSc Library is used to compute the pressure equation, using their Conjugate Gradient as a solver. We use OPENMPI/GNU/CUDA.

	IBM Power System S822LC						
	2x P8 10-cores + 2x K80 (2 G210 per K80)						
	CPU CPU/GPU CPU/GPU						
#C	T <sub>pres</sub> (s)	T <sub>pres</sub> (s)	SP	T <sub>total</sub> (s)	T <sub>total</sub> (s)	SP	
1	951.04	519.48	1.83	1022.18	630.54	1.62	
2	595.06	280.64	2.12	621.20	337.12	1.84	
4	245.62	145.73	1.68	263.61	173.95	1.51	
20	72.26	108.80	0.66	76.38	109.75	0.70	

If the GPUs are not overloaded, CPU+GPUs is cheaper.



## The PETSc Library is used to compute the pressure equation, using their Conjugate Gradient as a solver. We use OPENMPI/GNU/CUDA.

IBM Power System S824L						
	2x P8 12-cores + 2x K40 (1 G180 per K40)					
	CPU	CPU/GPU		CPU	CPU/GPU	
#C	T <sub>pres</sub> (s)	T <sub>pres</sub> (s)	SP	T <sub>total</sub> (s)	T <sub>total</sub> (s)	SP
1	1012.97	512.54	1.97	1087.75	637.86	1.71
2	632.45	267.82	2.36	659.71	327.81	2.01
4	248.33	163.51	1.52	267.82	189.04	1.42
24	54.12	106.19	0.65	57.81	112.82	0.51

If the GPUs are not overloaded, CPU+GPUs is cheaper.



## Conclusions – Future work

#### **Conclusions**

For 1 node only, using physical cores, much better performance on 2 different types of POWER8 nodes than on 1 x86 node

Some speedup observed using hardware threads (MPI only or MPI+OpenMP)

Comparison between PETSc (CPU) and PETSc (CPU+GPU) favourable to the latter

#### **Future work**

Test the code on several nodes & using meshes with other types of cells

Test the performance of the code when linked to AmgX (NVIDIA solver library)

Test newer hardware / software capability:

- GP100 "Pascal" GPU (more compute, better scheduling), NVLINK (GPU transfer performance)
- CUDA8 (better scheduling), Unified Memory (programmability, efficiency?)



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# THANK YOU! Any QUESTIONS?